# 3.12 Setting of detection angle

when detector use all-purpose bracket(accessory), take right picture as a example, adjust angle of installation to get detection range and performance which you want.

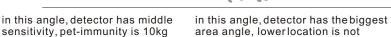




sensitivity, pet-immunity is 20kg









in this angle, detector has the smalle st area angle, and has high sensitivity, pet-immunity is unable.

### 3.13 Perform motion test to the detection area

- 1.Start the test at least 3 minutes after power supply
- 2.Crossing to any direction of the detection area, your walking with 0.75m/s will cause the Yellow&Green LED indicator to light for 2-3s (refer to the right diagram)
- Perform motion test from contrary directions in order to confirm the boundary of two sides. Make confirmed that detection center pointing to the center of protected area
- 4.Away from the detector 3 to 6m, raise slowly your arm and reach into the detection zone, mark the lower limit of PIR detection. Do the same step to confirm the upper limit
- 5.The center of detection zone should not uphill incline. To obtain a good detection range, please adjust the vertical detection range, ensure the detector is in a correct position
- 6.After MW sensitivity or detection angle are adjusted, walking test must be performed according to the above steps

# Masking detection test procedure(Anti-masking DIP7 ON)

in front of the detector with distance of 5cm, place a piece of white paper (or other objects);15s later, yellow light is flashing, AM output is on.

# Motion dectetion test procedure(DIP8 ON)

shaking detection, if detector is fixed on the wall, knock it by screw driver. AM port will open for  $2\sim3s$ 



important suggestion: in order to keep perfect work capability of detector, suggest user to give detector a walking test permonth.





#### 4. Special comments

Detector will false alarm if something happen as follow: direct current is unreliable, line connection error, cover lens balefully, optical system has been damaged, the temperature of surrounding towards to human's, detector will lose sensitivity and some parts lose function. but these problem not difficult to solved, we suggest user to test detector permonth, please do not see alarm system as insurance. possessor and leaseholder should treat your wealth carefully, although you have installed alarm system. According to specification of FCC, the 15th capture, our detector accord with regulation of grade B digital device, these regulation is proper protection for disturb uptown balefully. our device produce wireless frequency and energy, if using do not according to specification, will affect wireless and TV work normally. if interference is made(to confirm by open and turnoff), user can do as these methods:

- ----increase the distance between device and receiver.
- ----connect device to a interface of receiver which is different from the one which connect with power supply
- ----contact with wireless/TV technology engineer with experience



WARNING! Changes or modify to this unit not expressly approved by the party responsible for compliance could void the user authority to operate the equipment

# Installation Guide of FT-89 PIR&MW Intelligent Intrusion Detector

#### 1.Introduction

FT-89 series PIR&MW complex intrusion detector is the ideal motion detector for industrial, commercial, residence and so on, can be able to work in the most difficult environment conditions and where high security is required while maintaining

unprecedented immunity to false alarms, also can be work out door because good water-proof, FT-89 will inform user automatically if it be damaged or can not work normally. FT-89 series adopt precise Fresnel lens lens technology produce 3D protected area with high energy receiving rate and high sensitivity but no false alarm; combining four sources anti-mask microwave head, can calculate motion's volume, speed etc. so with high sensitivity distant range from 4m to 12m. FT-89 also adopt IR tube leading technology to make MW area and PIR area superposed. except special detect technology, FT-89 possesses protection device to avoid tampering or damaging. in it's working state, possesses functions as below:

- 1.active anti-shelter: using IR scanning, in order to avoiding object closing to detection area
- when choose OR mode, if PIR detector lose work ability caused by any problem (such as detector head be masked), MW partwill detect problem and send out alarm signal to control panel.
- 3.anti--damage: if some one moving and damaging detector, the shaking sensor can send out alarm signal to control panel.



Product appearance

# 2. Specifications

Models: FT-89(wired)

Detection Range:15m/25°C
Input Voltage:9to16VDC
current consumption:direct current about 65mA
(Lens Date)

optical lens date(RL300)
IR area:(11+11+9)\*2-62 (classic)
max covering area: (50\*50 foot)/90
start indication: three color light take turn
to flashing lastfor 60S

alarm, anti-tamper and anti-shield alarm output:fixed replay, NO and NC, more than 100mA/30V,--10 interior obstruct

anti-tamper interface: NC, 50mA/30VDC anti-shield output: fixed replay, NC, more than 100mA/30V,--10  $\Omega$ 

circuit open for 2~3S when alarming. alarm indication: red LED flashing for 2~3s

surface or corner of the wall, height:2.0~2.4 m(recommend height 2.2m) notice:bottom seat allows corner installation, and the angle can be 45 degree.

bracket 1: surface installation bracket, adjusted for up-90 degree,down-30 degree, right or left-45 degree.

work environment: work temperature:-10°C-50°C (14°F-122°F) preserve temperature:-20°C-60°C (4°F-140°F) anti-white light: higher than 15000LUX

Sise View

Microwave

0 2 4 6 8 10 15

Top View

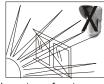
This device according to Europe legislature items of 1999/5/EC and requirements and spirit of wireless and telecommunication terminal device in Mar,9th,1999;also content demand of RSS-210 standard of Canada.

# 3.Installation

# 3.1 General Guidelines



do not confront co or hot source



do not confrontanywhere sunlight point-blank.



the lines of detector should apart from high voltage line.



do not installed in unstable place.



able place. metal v



# 3.2 Anti-pet installation



the top of detected area is not pet-immunity area



do not install detector confront the place whe pet can geteasily.



the pet which can be prevented should les than 20kg

— 1 —

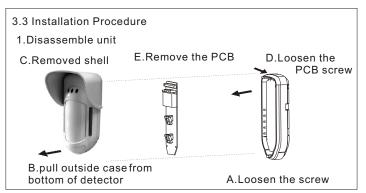


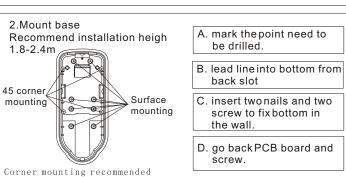
prevented should less than 15kg

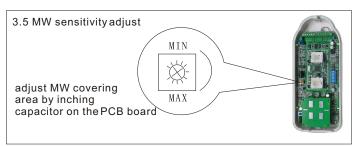


is from 2.2m to 2.4m.

P/N 20101223-3







# 3.6LED STATUS SPECIFICATION

LED	STATUS	DESCRIPTION		
Yellow	bright long time	indicate IR detect		
	flashing	indicate AM(anti-masking)detect		
Green	bright long time	indicate MW detect		
Red	bright long time	indicate alarming		
	flashing	indicate communication with BUS has trouble(only BUS output model)		
All LED	(successionally) flashing	initialization		

1. DIP switch should be in state "ON", start LED indication. 2.there is just one LED work anytime, for example:in one condition that both of PIR and MW are able to detect intrusion, yellow LED is bright or green LED is bright, then red LED will indicate alarming.

# 3.7DIP Switch set Default 1 2 3 4 5 6 7 8 DIP 1:LEDWorking status ON:LED ON

# DIP 2-3: Detection sensitiviy

İ	Sensitivity	DIP2	DIP3
	Low	0FF	0FF
	Middle	0FF	ON
	Normal	ON	0FF
	MAX(Default)	ON	ON

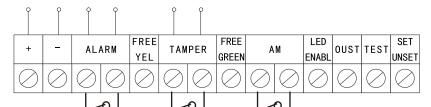
DIP 4: alarming qualification ON:PPIR or MW OFF:PIR +MW DIP 5:detector's optical capability ON:fence/long distance OFF:wide-angle DIP-6: red LED/three colors LED ON:only red LED

OFF:three color LED

DIP 7:anti-masking running ON:start OFF: stop DIP 8: prohibit swinging detector (if install swinging detector) ON:start OFF:stop

# 3.8Terminal wiring sepecification

OFF: LED OFF



+-	Power supply	12VDC		
ALARM	Alarm	N. C Relay, 24VDC, 0. 1A		
FREE YEL	Free interface, yellow	Free interface, can connect circuit and EOL resistor.		
TAMPER	Tamper switch	N. C Relay, 24VDC, 0. 1A		
AM Anti-masking		N.C AM RELAY output(24VDC,0.1A), Indicating anti masking or any fault of inside		
		Notes: When DIP 8 is ON,when swinging, this relay will be open -circuit instantly.		
FREE GREEN	Free interface, green	Free interface, can connect circuit and EOL resistor.		
LED ENABLE	ON	When DIP is on, used for LED remote control ON: input+12V or not connect OFF, connect input to OV		
OUST	DUST	NO.collector, MAX.70mA, indicating Lens is dirty and need cleaning.		
	Test	Supply OV voltage thru this interface, used for remote alarm test. Success: alarm relay open circuit instantly Failure: AM relay open circuit		
	ARM/DISARM	Enable the anti masking and make the LED status match the system status and arm/disarm. When systems is armed, this function can prevent intruder getting to knowthe detector status and disable anti-masking detection.		

SYS status	Input status	AM relay	LED
SET(ARM)	0٧	0FF	0FF
UNSET(DISARM)	12V or unconnection	0N*	0N**

\* DIP7 ON Anti masking ON

\*\* DIP1 ON(LEDON)和LED ENABLE Input terminal ON(+12V and unconnection)

— 2 —

#### 3.9 Change lens

# chang process

- 1.open cover using screwdriver.
- 2.aftering discharge 6 fixed screws back of frontal cover.
- 3.pull out fixed frame of lens, take down lens

FT-89back







4.change lens, input4 fixed fasteners in frame, matching the hole.

5.put lens frame back to cover, and fixed lens frame using screw.

6.install FT-89 out side over, and fix screw of cover.

put away lens frame from front-cover

take lens from frame

# 3.10 Model of Lens

FT-89front

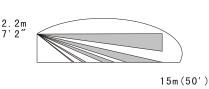
Wide-angle lens Wow location installation--Pet anti-immunity lens(RL300F)

Vertical View

15mm (50')

Wide-angle lens Side View

low position installed pet-immunity Lens(RL300F): Side View





15m(50')

Notice:Pets exempted;height of animal shorter than 70cm(2'4") no weight limited

Long distance lens(RL300LR): Vertical view



23m(75')

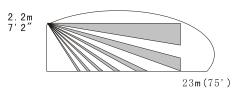
FenIceens(RL300B) Vertical view



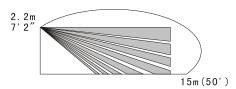
15m(50')



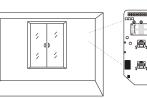
Long distance lens(RL300RL);Side elevation



FenIceens(RL300B) Side view



# 3.11 Setting of PCB



Please adjust interior PCB location to solve your problem when detector be installed in different environment and location, for example: if you want long distance detection, you should put PCB in higher position; if want short distance detection, please put PCB in lower positon.

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